

Video Lecture E12: Linear Independence in Theory

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Outline & Objectives

- Understand *linear dependence* informally as characterizing whether certain vectors are “redundant” in terms of creating linear combinations.
- Analyze the reasoning behind the definition of linear (in)dependence and one vector being a linear combination of others in the set.

Linear dependence & redundancy

Definition

A set of vectors $S = \{\vec{v}_1, \dots, \vec{v}_p\}$ is called **linearly independent** if the vector equation $x_1\vec{v}_1 + \dots + x_p\vec{v}_p = \vec{0}$ has only the trivial soln. (all $x_i = 0$). The set is **linearly dependent** if there exists a nontrivial solution, c_i not all zero, such that $c_1\vec{v}_1 + \dots + c_p\vec{v}_p = \vec{0}$. [\rightsquigarrow **linear dependence relation**]

Theorem

An indexed set $S = \{\vec{v}_1, \dots, \vec{v}_p\}$ of $p \geq 2$ vectors is linearly dependent \iff at least one vector is a linear combination of the others. In fact, if $\vec{v}_1 \neq \vec{0}$, then there is $j \geq 2$ such that $\vec{v}_j = d_1\vec{v}_1 + \dots + d_{j-1}\vec{v}_{j-1}$, some $d_i \in \mathbb{R}$.

Proof: (\Rightarrow) Suppose $\vec{v}_1 \neq \vec{0}$, and let $c_1\vec{v}_1 + \dots + c_p\vec{v}_p = \vec{0}$ be the linear dependence relation. Let j be the **largest** index such that $c_j \neq 0$ in the LDR. Then moving all previous terms to other side, we get $c_j\vec{v}_j = -c_1\vec{v}_1 - \dots - c_{j-1}\vec{v}_{j-1}$. Now divide through by c_j ,

Rewriting Example

The columns $\vec{a}_1, \vec{a}_2, \vec{a}_3$ of the following matrix are lin. dependent:

$$A = \begin{bmatrix} 1 & 5 & 3 \\ 3 & 7 & 1 \\ 2 & 5 & 1 \end{bmatrix} \rightsquigarrow 2 \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} - 1 \begin{bmatrix} 5 \\ 7 \\ 5 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} = 0.$$

So we can rewrite $\vec{a}_3 = -2\vec{a}_1 + \vec{a}_2$.

This also lets us simplify linear combinations. Suppose we know that $(11, 25, 17) = 2\vec{a}_1 + 3\vec{a}_2 - 2\vec{a}_3$. Then we can replace \vec{a}_3 with $-2\vec{a}_1 + \vec{a}_2$ to get:

$$(11, 25, 17) = 2\vec{a}_1 + 3\vec{a}_2 - 2(-2\vec{a}_1 + \vec{a}_2) = 6\vec{a}_1 + \vec{a}_2. \text{ (Check!)}$$

$$\text{So } \begin{bmatrix} 1 & 5 & 3 & | & b_1 \\ 3 & 7 & 1 & | & b_2 \\ 2 & 5 & 1 & | & b_3 \end{bmatrix} \text{ has a soln. } \iff \begin{bmatrix} 1 & 5 & | & b_1 \\ 3 & 7 & | & b_2 \\ 2 & 5 & | & b_3 \end{bmatrix} \text{ does,}$$

$$\text{i.e., } \text{Span}\{\vec{a}_1, \vec{a}_2, \vec{a}_3\} = \text{Span}\{\vec{a}_1, \vec{a}_2\}.$$

True or False?

- 1 **T/F:** If \vec{u}_2 is a scalar multiple of \vec{u}_1 , then $S = \{\vec{u}_1, \vec{u}_2\}$ is linearly dependent.
- 2 **T/F:** If $S = \{\vec{u}_1, \vec{u}_2\}$ is linearly dependent, then \vec{u}_2 is a multiple of \vec{u}_1 .
- 3 **T/F:** If the equation $A\vec{x} = \vec{b}$ has a solution (other than $\vec{x} = \vec{0}$), then the columns of A are linearly dependent.
- 4 **T/F:** If $\{w_1, w_2, w_3\}$ is linearly dependent, then so is $\{w_1, w_2, w_3, w_4\}$.