

Math 2110 MW 11:15-12:30, Th 12:30-1:45

Final Exam: Wed Dec 10, 12-2

13 Vectors and the Geometry of Space

13.1 Three Dimensional Coordinate Systems

Coordinate axes, Right-hand rule

Coordinate planes, octants

Distance formula

Sphere

805/1, 3, 5, 7, 9, 11, 15, 23, 25, 35

805/13, 17, 29, 30, 37

13.2 Vectors

Vector (magnitude, direction), initial point, terminal point

Addition (Parallelogram Law), scalar multiplication, subtraction

Components, Position vector (from origin)

Length, magnitude

Properties: commutative, associative (addition, scalar multiplication), 0, inverse, distributive, multiplication by 1

Standard basis vectors $\mathbf{i}, \mathbf{j}, \mathbf{k}$

Unit vector

813/1, 3, 4, 7, 13, 17, 19, 23, 27, 31, 35

813/9, 15, 21, 29, 30, 39, 43

13.3 Dot Product

Definition

Properties: $\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$, commutative, distributive, scalar multiplication, $\mathbf{0} \cdot \mathbf{a} = 0$

$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}||\mathbf{b}| \cos \theta$ (Proof-Law of Cosines)

Orthogonal

Direction angles α, β, γ

Direction cosines

$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$

Scalar projection $\text{comp}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|}$

Vector projection $\text{proj}_{\mathbf{a}} \mathbf{b} = \left(\frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|} \right) \frac{\mathbf{a}}{|\mathbf{a}|} = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|^2} \mathbf{a}$

820/1, 3, 5, 7, 15, 21, 23, 27, 29, 35, 47, 57

820/9, 17, 31, 37, 41, 49, 58

13.4 Cross Product

Definition, mnemonic using determinants

$\mathbf{a} \times \mathbf{b}$ orthogonal to \mathbf{a} and \mathbf{b} .

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}| \sin \theta \quad (\text{Proof - } |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2|\mathbf{b}|^2 - (\mathbf{a} \cdot \mathbf{b})^2)$$

Length of cross product = area of parallelogram

Properties: anti-commutative, multiplication by scalar, distributive, triple product, $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$

Volume of parallopiped = scalar triple product

Torque $\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$

828/1, 9, 15, 17, 23, 25

828/3, 33, 39, 45

13.5 Equations of Lines and Planes

Lines

Vector Equation $\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$

Parametric Equations $x = x_0 + at, y = y_0 + bt, z = z_0 + ct$

Direction Numbers

$$\text{Symmetric Equations } \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

Line segment: restrict t

838/1, 3, 7, 15, 19

838/5, 9, 17, 21

Planes

Normal vector

Vector equation: $\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$

Scalar equation: $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$

Parallel, orthogonal planes

Distance from point to plane $\frac{|\mathbf{n} \cdot \mathbf{b}|}{|\mathbf{n}|}$

838/23, 25, 39, 47, 53, 55

838/27, 33, 41, 49, 54

13.6 Cylinders and Quadric Surfaces

Definition: Cylinder - lines parallel to a given line passing through a place curve

Quadric surface - graph of second degree equation in three variables

Ellipsoid, elliptic paraboloid, hyperbolic paraboloid, hyperboloid of one sheet, hyperboloid of two sheets

849/1, 3, 5, 9, 11, 13, 21-28, 29

849/15, 31

14 Vector Functions

14.1 Vector Functions and Space Curves

Vector Valued Function $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$

Limit, continuity

Space curves, parametric equations

858/1, 3, 7, 15, 19-24

858/9, 11, 25, 39

14.2 Derivatives and Integrals of Vector Functions

Definition - derivative, integral

Tangent line, unit tangent $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|}$

Smooth curve: \mathbf{r}' is continuous and non-zero

Properties of derivatives: term-by-term, product and chain rules.

864/1, 3, 9, 11, 17, 23, 31, 33

864/5, 8, 15, 19, 27, 35, 37

14.3 Arc Length and Curvature

$$L = \int_a^b |\mathbf{r}'(t)| dt$$

Arc length function $s(t) = \int_a^t |\mathbf{r}'(u)| du$

$$\frac{ds}{dt} = |\mathbf{r}'(t)|$$

Parametrize curve with respect to arc length: Solve for t in terms of s

$$\text{Curvature: } \kappa = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{|\mathbf{T}'(t)|}{|\mathbf{r}'(t)|}$$

$$\kappa(t) = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}$$

For plane curve $y = f(x)$, $\kappa(x) = \frac{|f''(x)|}{[1 + (f'(x))^2]^{3/2}}$

$$\text{Normal Vector } \mathbf{N}(t) = \frac{\mathbf{T}'(t)}{|\mathbf{T}'(t)|}$$

Binormal vector $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$

Normal plane - determined by \mathbf{N} and \mathbf{B}

Osculating plane - determined by \mathbf{T} and \mathbf{N}

872/1, 3, 13, 37, 39

872/5, 15, 27

14.4 Motion in Space: Velocity and Acceleration

$$\mathbf{v}(t) = \mathbf{r}'(t)$$

$$\mathbf{a}(t) = \mathbf{v}'(t)$$

Newton's Second Law of Motion: $\mathbf{F} = m\mathbf{a}$

$$\mathbf{a} = v'\mathbf{T} + \kappa v^2\mathbf{N}$$

882/1, 3, 5, 9, 19, 23, 31

882/7, 11, 25, 33

15 Partial Derivatives

15.1 Functions of Several Variables

Definition 1 (Function of Two Variables). $f(x, y)$

Independent variables, dependent variable

Domain, range

Graph

Contour or Level Curves - graphs of $f(x, y) = k$

Functions of three or more variables

Three views: function of n real variables x_1, x_2, \dots, x_n , function of a single point variable (x_1, x_2, \dots, x_n) , function of a vector variable $\mathbf{x} = \langle x_1, x_2, \dots, x_n \rangle$

901/1, 3, 5, 7, 11, 21

901/9, 15, 25

15.2 Limits and Continuity

Definition $\lim_{(x,y) \rightarrow (a,b)} f(x, y) = L$

Definition - Continuity

Functions of three or more variables

913/1, 5, 7, 19, 27, 29, 37

913/9, 11, 31

15.3 Partial Derivatives

Definition $f_x(a, b)$, $f_y(a, b)$, $f_x(x, y)$, $f_y(x, y)$

Notations: f_x , $\frac{\partial f}{\partial x}$, $\frac{\partial z}{\partial x}$, f_1 , $D_1 f$, $D_x f$

Functions of more than two variables

Higher Derivatives

$$\text{Notation: } (f_x)_y = f_{xy} = f_{12} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial^2 z}{\partial y \partial x}$$

Theorem 1 (Clairaut's Theorem). *If f_{xy} and f_{yx} are both continuous on a disk containing (a, b) , then $f_{xy}(a, b) = f_{yx}(a, b)$.*

924/1, 13, 15, 35, 41, 45, 53

924/17, 19, 37, 47, 57

15.4 Tangent Planes and Linear Approximations

Tangent Plane: $z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$ (If partial derivatives are continuous.)

Linear or Tangent Plane Approximation

Definition: f differentiable if $\Delta z = f_x(a, b)\Delta x + f_y(a, b)\Delta y + \epsilon_1\Delta x + \epsilon_2\Delta y$ where $\epsilon_1 \rightarrow 0$ and $\epsilon_2 \rightarrow 0$ as $(\Delta x, \Delta y) \rightarrow (0, 0)$.

Theorem 2. *Partials continuous nearby implies function differentiable.*

Total differential: $dz = f_x(x, y)dx + f_y(x, y)dy$

935/1, 3, 7, 11, 17, 23, 29, 31

935/5, 13, 25, 33

15.5 Chain Rule

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}, \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

Implicit Differentiation:

$$y = f(x) \text{ defined by } F(x, y) = 0 \text{ implies } \frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0 \text{ implies } \frac{dy}{dx} = -\frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial y}} = -\frac{F_x}{F_y}.$$

$$z = f(x, y) \text{ defined by } F(x, y, z) = 0 \implies \frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$$

943/1, 3, 7, 13, 21, 35

943/5, 9, 11, 23, 45

15.6 Directional Derivatives and the Gradient Vector

Definition 2 (Directional Derivative). *Unit vector* $\mathbf{u} = \langle a, b \rangle$,

$$D_{\mathbf{u}}f(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + ha, y_0 + hb) - f(x_0, y_0)}{h}.$$

Theorem 3. $D_{\mathbf{u}}f(x, y) = f_x(x, y)a + f_y(x, y)b$

$$D_{\mathbf{u}}f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle \cdot \mathbf{u}.$$

Definition 3 (Gradient). $\text{grad}f = \nabla f = \langle f_x, f_y \rangle$

Theorem 4. *Maximum value of directional derivative is $|\nabla f|$ and occurs in the direction of ∇f .*

Tangent plane to level surface $F(x, y, z) = k$: $\nabla F \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$

Tangent plane to $z = f(x, y)$: $z - z_0 = f_x(x - x_0) + f_y(y - y_0)$

956/1, 5, 7, 11, 13, 21, 27

956/9, 15, 23, 29

15.7 Maximum and Minimum Values

Definition: local maximum, local minimum, absolute maximum, absolute minimum

Theorem 5. f has local extremum and partials exist \implies partials equal 0.

Critical point (stationary point) - partials are 0 or a partial doesn't exist

Second Derivative Test: Critical point, second partials continuous, $D = f_{xx}f_{yy} - (f_{xy})^2$.

- $D > 0$, $f_{xx} > 0$ implies local minimum
- $D > 0$, $f_{xx} < 0$ implies local maximum
- $D < 0$ implies saddle point

f continuous on closed set implies f has absolute extrema

966/1, 5, 7, 27, 35, 37, 43

966/9, 15, 29, 39, 45, 48

15.8 Lagrange Multipliers

Find extrema for $f(x, y, z)$ subject to constraint $g(x, y, z) = k$.

Solve: $\nabla f = \lambda \nabla g$, $g(x, y, z) = k$.

Two constraints $g(x, y, z) = k$, $h(x, y, z) = c$: Solve $\nabla f = \lambda \nabla g + \mu \nabla h$

976/3, 7

976/5, 9

16 Multiple Integrals

16.1 Double Integrals Over Rectangles

Riemann Sum $\sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A_{ij}$

Definition: $\int \int_R f(x, y) dA = \lim_{m, n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) \Delta A_{ij}$

Application: Volume

Numerical calculation: Midpoint Rule

Properties: $\int \int_R f(x, y) \pm g(x, y) dA$, $\int \int_R k f(x, y) dA$

$f(x, y) \geq g(x, y) \implies \int \int_R f(x, y) dA \geq \int \int_R g(x, y) dA$

994/1, 3, 11

994/13, 14

16.2 Iterated Integrals

Iterated Integral

Theorem 6 (Fubini's Theorem). *If f is continuous on a rectangle R , $\int \int_R f(x, y) dA = \int_a^b \int_c^d f(x, y) dy dx = \int_c^d \int_a^b f(x, y) dx dy$.*

1000/1, 3, 11, 13

1000/5, 9, 15

16.3 Double Integrals over General Regions

If region D lies in a rectangle R , define $F(x, y) = \begin{cases} f(x, y) & \text{if } (x, y) \in R \\ 0 & \text{if } (x, y) \notin R. \end{cases}$

Type I Region: Between two functions, vertical sides - convert to iterated integral

Type II Region: Horizontal sides

Properties: Sum or difference, multiplication by constant, $f(x, y) \geq g(x, y)$, integral over union of non-overlapping regions, $m \leq f(x, y) \leq M$

1008/1, 7, 9, 19

1008/3, 11, 13, 37

16.4 Double Integrals in Polar Coordinates

$\iint_R f(x, y) dA = \int_{\alpha}^{\beta} \int_a^b f(r \cos \theta, r \sin \theta) r dr d\theta$

1014/1-3, 7, 9, 17, 21, 29

1014/4-6, 11, 15, 19, 23, 31, 33

16.5 Applications of Double Integrals

Density and mass

Moments and center of mass

Moment of inertia

1024/3, 5, 11

1024/7, 15

16.6 Triple Integrals

Definition

Turn into iterated integral

Applications:

Volume = $\iiint_E dV$

Mass, center of mass, moments, centroid, moment of inertia

1035/1, 3, 7, 9, 17

1035/5, 11, 25, 27

16.7 Triple Integrals in Cylindrical Coordinates

$dV \rightarrow r dz dr d\theta$

1040/1,3, 7,9, 15, 23

1040/5, 17, 19, 25, 27

16.8 Triple Integrals in Spherical Coordinates

$dV \rightarrow \rho^2 \sin \phi d\rho d\theta d\phi$

1046/1,3,6, 7,9,11, 15, 21

1046/5,13, 17, 19, 33, 39

16.9 Change of Variables in Multiple Integrals

Transformation $T(u, v) = (x, y)$

$x = g(u, v)$, $y = h(u, v)$ or $x = x(u, v)$, $y = y(u, v)$

Let S be rectangle with sides $(\Delta u, \Delta v)$. Image $R = T(S)$ is approximately a rectangle with

sides $\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u} \rangle \Delta u$, $\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v} \rangle \Delta v$.

Area is approximately the Jacobian $\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \Delta u \Delta v$.

So $\Delta A \approx \frac{\partial(x, y)}{\partial(u, v)} \Delta u \Delta v$.

$$\iint_R f(x, y) dA = \iint_S f(g(u, v), h(u, v)) \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} du dv.$$

Example: Change to polar coordinates.

Triple Integrals

1057/1, 7, 11, 15, 17

1057/3, 5, 9, 13, 23, 35

17 Vector Calculus

17.1 Vector Fields

Definition 4 (Vector Field). *Vector function \mathbf{F} assigning $(x, y) \rightarrow \mathbf{F}(x, y)$.*

Examples: velocity field, gravitational field, force field, gradient vector field

Definition 5 (Conservative Vector Field). *\mathbf{F} is conservative if $\mathbf{F} = \nabla f$ for some potential function f .*

1068/1, 11-14, 21

1068/3, 15-18, 25

17.2 Line Integrals

Definition: $\int_C f(x, y) ds$ in terms of Riemann Sum.

Calculation: $ds = \sqrt{\frac{dx^2}{dt} + \frac{dy^2}{dt}}$

Example: Mass of wire, center of mass

Variations: $\int_C f(x, y) dx$, $\int_C f(x, y) dy$, $\int_C P(x, y) dx + Q(x, y) dy$

Line integrals in space

Line integrals of vector fields: Work = $\int_C \mathbf{F} \cdot \mathbf{T} ds$

Definition 6 (Line Integral of \mathbf{F} along C). $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_C \mathbf{F} \cdot \mathbf{T} ds$.

1079/1, 3, 9, 17, 19, 31

1079/5, 7, 11, 21, 39

17.3 Fundamental Theorem for Line Integrals

Theorem 7. $\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$

Definition: Independence of path

Independent of path if and only if integral along any closed path is 0.

Theorem: $\int_C \mathbf{F} \cdot d\mathbf{r}$ independent of path $\implies \mathbf{F}$ is a conservative vector field.

Theorem: $\mathbf{F} = \langle P, Q \rangle$ conservative $\implies \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$.

Simple curve, simply connected

Theorem: $\mathbf{F} = \langle P, Q \rangle$ on open simply-connected region and $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \implies \mathbf{F}$ is conservative.

1089/1, 3, 5, 13, 15, 19

1089/7, 17, 21, 33

17.4 Green's Theorem

Theorem 8 (Green's Theorem). $\int_{\partial D} P dx + Q dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$

1096/1, 7, 13

1096/3, 9, 15

17.5 Curl and Divergence

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

Theorem 9. If f has continuous second-order partial derivatives, $\nabla \times (\nabla f) = \mathbf{0}$

Corollary: If \mathbf{F} is conservative, then $\nabla \times \mathbf{F} = \mathbf{0}$.

Definition 7 (Divergence). $\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$.

Theorem 10. $\nabla \cdot \nabla \times \mathbf{F} = 0$

Vector Form of Green's Theorem: $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D (\nabla \times \mathbf{F}) \cdot \mathbf{k} dA$.

$$\oint_C \mathbf{F} \cdot \mathbf{n} ds = \iint_D \nabla \cdot \mathbf{F} dA$$

1104/1, 3, 13, 23

1104/5, 7, 31

17.6 Parametric Surfaces and their Areas

Parametric Surface $x = x(u, v)$, $y = y(u, v)$, $z = z(u, v)$

Surface of revolution - from $y = f(x)$: $x = x$, $y = f(x) \cos \theta$, $z = f(x) \sin \theta$.

Tangent planes: use tangent vectors $\left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$, $\left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$

Surface area - of surface given by $\mathbf{r}(u, v)$

$$\text{Area is } \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA$$

1114/1, 11-16, 19, 35

1114/3, 23, 39

17.7 Surface Integrals

$\iint_S f(x, y, z) dS$ as a Riemann Sum

For surface $z = g(x, y)$, $\iint_S f(x, y, z) dS = \iint_D f(x, y, g(x, y)) \sqrt{\frac{\partial z^2}{\partial x^2} + \frac{\partial z^2}{\partial y^2} + 1} dA$

In general, $dS \rightarrow |\mathbf{r}_u \times \mathbf{r}_v| dA$

Surface integral of vector field $\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S \mathbf{F} \cdot \mathbf{n} dS$. Called flux of \mathbf{F} across S .

1127/5, 7, 19

1127/9, 11, 21

17.8 Stokes' Theorem

Theorem 11 (Stokes' Theorem). $\iint_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S} = \int_{\partial S} \mathbf{F} \cdot d\mathbf{r}$.

1133/3, 7, 13

1133/5, 9, 17

17.9 Divergence Theorem

Theorem 12 (Divergence Theorem). $\iint_{\partial E} \mathbf{F} \cdot d\mathbf{S} = \iiint_E \nabla \cdot \mathbf{F} dV.$

1139/1, 3, 7, 22

1139/5, 9, 23