

# Math 210 MW 11:15-12:30, Th 12:30-1:45

## 13 Vectors and the Geometry of Space

### 13.1 Three Dimensional Coordinate Systems

Coordinate axes, Right-hand rule

Coordinate planes, octants

Distance formula

Sphere

805/1, 3, 5, 7, 9, 11, 15, 23, 25, 35

805/13, 17, 29, 30, 37

### 13.2 Vectors

Vector (magnitude, direction), initial point, terminal point

Addition (Parallelogram Law), scalar multiplication, subtraction

Components, Position vector (from origin)

Length, magnitude

Properties: commutative, associative (addition, scalar multiplication), 0, inverse, distributive, multiplication by 1

Standard basis vectors  $\mathbf{i}, \mathbf{j}, \mathbf{k}$

Unit vector

813/1, 3, 4, 7, 13, 17, 19, 23, 27, 31, 35

813/9, 15, 21, 29, 30, 39, 43

### 13.3 Dot Product

Definition

Properties:  $\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$ , commutative, distributive, scalar multiplication,  $\mathbf{0} \cdot \mathbf{a} = 0$

$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}||\mathbf{b}| \cos \theta$  (Proof-Law of Cosines)

Orthogonal

Direction angles  $\alpha, \beta, \gamma$

Direction cosines

$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$

Scalar projection  $\text{comp}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|}$

Vector projection  $\text{proj}_{\mathbf{a}} \mathbf{b} = \left( \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|} \right) \frac{\mathbf{a}}{|\mathbf{a}|} = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|^2} \mathbf{a}$

820/1, 3, 5, 7, 15, 21, 23, 27, 29, 35, 47, 57

820/9, 17, 31, 37, 41, 49, 58

### 13.4 Cross Product

Definition, mnemonic using determinants

$\mathbf{a} \times \mathbf{b}$  orthogonal to  $\mathbf{a}$  and  $\mathbf{b}$ .

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}| \sin \theta \text{ (Proof - } |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2|\mathbf{b}|^2 - (\mathbf{a} \cdot \mathbf{b})^2 \text{)}$$

Length of cross product = area of parallelogram

Properties: anti-commutative, multiplication by scalar, distributive, triple product,  $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$

Volume of parallopiped = scalar triple product

$$\text{Torque } \boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$$

828/1, 9, 15, 17, 23, 25

828/3, 33, 39, 45

### 13.5 Equations of Lines and Planes

#### Lines

Vector Equation  $\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$

Parametric Equations  $x = x_0 + at, y = y_0 + bt, z = z_0 + ct$

Direction Numbers

$$\text{Symmetric Equations } \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

Line segment: restrict  $t$

838/1, 3, 7, 15, 19

838/5, 9, 17, 21

#### Planes

Normal vector

$$\text{Vector equation: } \mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

$$\text{Scalar equation: } a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

Parallel, orthogonal planes

$$\text{Distance from point to plane } \frac{|\mathbf{n} \cdot \mathbf{b}|}{|\mathbf{n}|}$$

838/23, 25, 39, 47, 53, 55

838/27, 33, 41, 49, 54

### 13.6 Cylinders and Quadric Surfaces

Definition: Cylinder - lines parallel to a given line passing through a place curve

Quadric surface - graph of second degree equation in three variables

Ellipsoid, elliptic paraboloid, hyperbolic paraboloid, hyperboloid of one sheet, hyperboloid of two sheets

849/1, 3, 5, 9, 11, 13, 21-28, 29

849/15, 31

## 14 Vector Functions

### 14.1 Vector Functions and Space Curves

Vector Valued Function  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$

Limit, continuity

Space curves, parametric equations

858/1, 3, 7, 15, 19-24

858/9, 11, 25, 39

### 14.2 Derivatives and Integrals of Vector Functions

Definition - derivative, integral

Tangent line, unit tangent  $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|}$

Smooth curve:  $\mathbf{r}'$  is continuous and non-zero

Properties of derivatives: term-by-term, product and chain rules.

864/1, 3, 9, 11, 17, 23, 31, 33

864/5, 8, 15, 19, 27, 35, 37

### 14.3 Arc Length and Curvature

$$L = \int_a^b |\mathbf{r}'(t)| dt$$

Arc length function  $s(t) = \int_a^t |\mathbf{r}'(u)| du$

$$\frac{ds}{dt} = |\mathbf{r}'(t)|$$

Parametrize curve with respect to arc length: Solve for  $t$  in terms of  $s$

$$\text{Curvature: } \kappa = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{|\mathbf{T}'(t)|}{|\mathbf{r}'(t)|}$$

$$\kappa(t) = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3}$$

$$\text{For plane curve } y = f(x), \kappa(x) = \frac{|f''(x)|}{[1 + (f'(x))^2]^{3/2}}$$

$$\text{Normal Vector } \mathbf{N}(t) = \frac{\mathbf{T}'(t)}{|\mathbf{T}'(t)|}$$

$$\text{Binormal vector } \mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$$

Normal plane - determined by  $\mathbf{N}$  and  $\mathbf{B}$

Osculating plane - determined by  $\mathbf{T}$  and  $\mathbf{N}$

872/1, 3, 13, 37, 39

872/5, 15, 27

## 14.4 Motion in Space: Velocity and Acceleration

$$\mathbf{v}(t) = \mathbf{r}'(t)$$

$$\mathbf{a}(t) = \mathbf{v}'(t)$$

Newton's Second Law of Motion:  $\mathbf{F} = m\mathbf{a}$

$$\mathbf{a} = v'\mathbf{T} + \kappa v^2\mathbf{N}$$

882/1, 3, 5, 9, 19, 23, 31

882/7, 11, 25, 33

## 15 Partial Derivatives

### 15.1 Functions of Several Variables

**Definition 1** (Function of Two Variables).  $f(x, y)$

Independent variables, dependent variable

Domain, range

Graph

Contour or Level Curves - graphs of  $f(x, y) = k$

Functions of three or more variables

Three views: function of  $n$  real variables  $x_1, x_2, \dots, x_n$ , function of a single point variable  $(x_1, x_2, \dots, x_n)$ , function of a vector variable  $\mathbf{x} = \langle x_1, x_2, \dots, x_n \rangle$

901/1, 3, 5, 7, 11, 21

901/9, 15, 25

### 15.2 Limits and Continuity

Definition  $\lim_{(x,y) \rightarrow (a,b)} f(x, y) = L$

Definition - Continuity

Functions of three or more variables

913/1, 5, 7, 19, 27, 29, 37

913/9, 11, 31

### 15.3 Partial Derivatives

Definition  $f_x(a, b)$ ,  $f_y(a, b)$ ,  $f_x(x, y)$ ,  $f_y(x, y)$

Notations:  $f_x$ ,  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial z}{\partial x}$ ,  $f_1$ ,  $D_1 f$ ,  $D_x f$

Functions of more than two variables

Higher Derivatives

$$\text{Notation: } (f_x)_y = f_{xy} = f_{12} = \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial^2 z}{\partial y \partial x}$$

**Theorem 1** (Clairaut's Theorem). *If  $f_{xy}$  and  $f_{yx}$  are both continuous on a disk containing  $(a, b)$ , then  $f_{xy}(a, b) = f_{yx}(a, b)$ .*

924/1, 13, 15, 35, 41, 45, 53

924/17, 19, 37, 47, 57

### 15.4 Tangent Planes and Linear Approximations

Tangent Plane:  $z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$  (If partial derivatives are continuous.)

Linear or Tangent Plane Approximation

Definition:  $f$  differentiable if  $z = f(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b) + \epsilon_1(x - a) + \epsilon_2(y - b)$  where  $\epsilon_1 \rightarrow 0$  and  $\epsilon_2 \rightarrow 0$  as  $(x, y) \rightarrow (a, b)$ .

**Theorem 2.** *Partial derivatives continuous nearby implies function differentiable.*

Total differential:  $dz = f_x(x, y)dx + f_y(x, y)dy$

935/1, 3, 7, 11, 17, 23, 29, 31

935/5, 13, 25, 33

### 15.5 Chain Rule

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} = \frac{\partial z}{\partial x} \frac{dx}{ds} \frac{ds}{dt} + \frac{\partial z}{\partial y} \frac{dy}{ds} \frac{ds}{dt}, \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

Implicit Differentiation:

$$y = f(x) \text{ defined by } F(x, y) = 0 \text{ implies } \frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0 \text{ implies } \frac{dy}{dx} = -\frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial y}} = -\frac{F_x}{F_y}.$$

$$z = f(x, y) \text{ defined by } F(x, y, z) = 0 \implies \frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$$

943/1, 3, 7, 13, 21, 35

943/5, 9, 11, 23, 45

## 15.6 Directional Derivatives and the Gradient Vector

**Definition 2** (Directional Derivative). Unit vector  $\mathbf{u} = \langle a, b \rangle$ ,

$$D_{\mathbf{u}}f(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + ha, y_0 + hb) - f(x_0, y_0)}{h}.$$

**Theorem 3.**  $D_{\mathbf{u}}f(x, y) = f_x(x, y)a + f_y(x, y)b$

$$D_{\mathbf{u}}f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle \cdot \mathbf{u}.$$

**Definition 3** (Gradient).  $\text{grad}f = \nabla f = \langle f_x, f_y \rangle$

**Theorem 4.** Maximum value of directional derivative is  $|\nabla f|$  and occurs in the direction of  $\nabla f$ .

Tangent plane to level surface  $F(x, y, z) = k$ :  $\nabla F \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$

Tangent plane to  $z = f(x, y)$ :  $z - z_0 = f_x(x - x_0) + f_y(y - y_0)$

956/1, 5, 7, 11, 13, 21, 27

956/9, 15, 23, 29

## 15.7 Maximum and Minimum Values

Definition: local maximum, local minimum, absolute maximum, absolute minimum

**Theorem 5.**  $f$  has local extremum and partials exist  $\implies$  partials equal 0.

Critical point (stationary point) - partials are 0 or a partial doesn't exist

Second Derivative Test: Critical point, second partials continuous,  $D = f_{xx}f_{yy} - (f_{xy})^2$ .

- $D > 0, f_{xx} > 0$  implies local minimum
- $D > 0, f_{xx} < 0$  implies local maximum
- $D < 0$  implies saddle point

$f$  continuous on closed set implies  $f$  has absolute extrema

966/1, 5, 7, 27, 35, 37, 43

966/9, 15, 29, 39, 45, 48

## 15.8 Lagrange Multipliers

Find extrema for  $f(x, y, z)$  subject to constraint  $g(x, y, z) = k$ .

Solve:  $\nabla f = \lambda \nabla g, g(x, y, z) = k$ .

Two constraints  $g(x, y, z) = k, h(x, y, z) = c$ : Solve  $\nabla f = \lambda \nabla g + \mu \nabla h$

976/3, 7

976/5, 9

## 16 Multiple Integrals

### 16.1 Double Integrals Over Rectangles

Riemann Sum  $\sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) A_{ij}$

Definition:  $\int \int_R f(x, y) dA = \lim_{m, n \rightarrow \infty} \sum_{i=1}^m \sum_{j=1}^n f(x_{ij}^*, y_{ij}^*) A_{ij}$

Application: Volume

Numerical calculation: Midpoint Rule

Properties:  $\int \int_R f(x, y) \pm g(x, y) dA$ ,  $\int \int_R k f(x, y) dA$

$f(x, y) \geq g(x, y) \implies \int \int_R f(x, y) dA \geq \int \int_R g(x, y) dA$

994/1, 3, 11

994/13, 14

### 16.2 Iterated Integrals

Iterated Integral

**Theorem 6** (Fubini's Theorem). *If  $f$  is continuous on a rectangle  $R$ ,  $\int \int_R f(x, y) dA = \int_a^b \int_c^d f(x, y) dy dx = \int_c^d \int_a^b f(x, y) dx dy$ .*

1000/1, 3, 11, 13

1000/5, 9, 15

### 16.3 Double Integrals over General Regions

If region  $D$  lies in a rectangle  $R$ , define  $F(x, y) = \begin{cases} f(x, y) & \text{if } (x, y) \in R \\ 0 & \text{if } (x, y) \notin R. \end{cases}$

Type I Region: Between two functions, vertical sides - convert to iterated integral

Type II Region: Horizontal sides

Properties: Sum or difference, multiplication by constant,  $f(x, y) \geq g(x, y)$ , integral over union of non-overlapping regions,  $m \leq f(x, y) \leq M$

1008/1, 7, 9, 19

1008/3, 11, 13, 37

### 16.4 Double Integrals in Polar Coordinates

$\iint_R f(x, y) dA = \int_{\alpha}^{\beta} \int_a^b f(r \cos \theta, r \sin \theta) r dr d\theta$

1014/1-3, 7, 9, 17, 21, 29

1014/4-6, 11, 15, 19, 23, 31, 33

## 16.5 Applications of Double Integrals

Density and mass

Moments and center of mass

Moment of inertia

1024/3, 5, 11

1024/7, 15

## 16.6 Triple Integrals

Definition

Turn into iterated integral

Applications:

Volume =  $\iiint_E dV$

Mass, center of mass, moments, centroid, moment of inertia

1035/1, 3, 7, 9, 17

1035/5, 11, 25, 27

## 16.7 Triple Integrals in Cylindrical Coordinates

$dV \rightarrow r \, dz \, dr \, d\theta$

1040/1,3, 7,9, 15, 23

1040/5, 17, 19, 25, 27

## 16.8 Triple Integrals in Spherical Coordinates

$dV \rightarrow \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$

1046/1,3,6, 7,9,11, 15, 21

1046/5,13, 17, 19, 33, 39



## 16.9 Change of Variables in Multiple Integrals

Transformation  $T(u, v) = (x, y)$

$x = g(u, v)$ ,  $y = h(u, v)$  or  $x = x(u, v)$ ,  $y = y(u, v)$

Let  $S$  be rectangle with sides  $(-u, u)$ ,  $(-v, v)$ . Image  $R = T(S)$  is approximately a rectangle with

sides  $\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u} \rangle$   $u$ ,  $\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v} \rangle$   $v$ .

Area is approximately the Jacobian  $\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} u \quad v$ .

So  $A \approx \frac{\partial(x, y)}{\partial(u, v)} u \quad v$ .

$$\iint_R f(x, y) dA = \iint_S f(g(u, v), h(u, v)) \left\| \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \right\| du dv.$$

Example: Change to polar coordinates.

Triple Integrals

1057/1, 7, 11, 15, 17

1057/3, 5, 9, 13, 23, 35

## 17 Vector Calculus

### 17.1 Vector Fields

**Definition 4** (Vector Field). *Vector function  $\mathbf{F}$  assigning  $(x, y) \rightarrow \mathbf{F}(x, y)$ .*

Examples: velocity field, gravitational field, force field, gradient vector field

**Definition 5** (Conservative Vector Field).  *$\mathbf{F}$  is conservative if  $\mathbf{F} = \nabla f$  for some potential function  $f$ .*

1068/1, 11-14, 21

1068/3, 15-18, 25

## 17.2 Line Integrals

Definition:  $\int_C f(x, y) ds$  in terms of Riemann Sum.

Calculation:  $ds = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$

Example: Mass of wire, center of mass

Variations:  $\int_C f(x, y) dx$ ,  $\int_C f(x, y) dy$ ,  $\int_C P(x, y) dx + Q(x, y) dy$

Line integrals in space

Line integrals of vector fields: Work =  $\int_C \mathbf{F} \cdot \mathbf{T} ds$

**Definition 6** (Line Integral of  $\mathbf{F}$  along  $C$ ).  $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_C \mathbf{F} \cdot \mathbf{T} ds$ .

1079/1, 3, 9, 17, 19, 31

1079/5, 7, 11, 21, 39

## 17.3 Fundamental Theorem for Line Integrals

**Theorem 7.**  $\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$

Definition: Independence of path

Independent of path if and only if integral along any closed path is 0.

Theorem:  $\int_C \mathbf{F} \cdot d\mathbf{r}$  independent of path  $\implies \mathbf{F}$  is a conservative vector field.

Theorem:  $\mathbf{F} = \langle P, Q \rangle$  conservative  $\implies \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$ .

Simple curve, simply connected

Theorem:  $\mathbf{F} = \langle P, Q \rangle$  on open simply-connected region and  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \implies \mathbf{F}$  is conservative.

1089/1, 3, 5, 13, 15, 19

1089/7, 17, 21, 33

## 17.4 Green's Theorem

**Theorem 8** (Green's Theorem).  $\int_{\partial D} P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$

1096/1, 7, 13

1096/3, 9, 15

## 17.5 Curl and Divergence

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

**Theorem 9.** If  $f$  has continuous second-order partial derivatives,  $\nabla \times (\nabla f) = \mathbf{0}$

Corollary: If  $\mathbf{F}$  is conservative, then  $\nabla \times \mathbf{F} = \mathbf{0}$ .

**Definition 7** (Divergence).  $\text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$ .

**Theorem 10.**  $\nabla \cdot \nabla \times \mathbf{F} = 0$

Vector Form of Green's Theorem:  $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D (\nabla \times \mathbf{F}) \cdot \mathbf{k} dA$ .

$$\oint_C \mathbf{F} \cdot \mathbf{n} ds = \iint_D \nabla \cdot \mathbf{F} dA$$

1104/1, 3, 13, 23

1104/5, 7, 31

## 17.6 Parametric Surfaces and their Areas

Parametric Surface  $x = x(u, v)$ ,  $y = y(u, v)$ ,  $z = z(u, v)$

Surface of revolution - from  $y = f(x)$ :  $x = x$ ,  $y = f(x) \cos \theta$ ,  $z = f(x) \sin \theta$ .

Tangent planes: use tangent vectors  $\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \rangle$ ,  $\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \rangle$

Surface area - of surface given by  $\mathbf{r}(u, v)$

$$\text{Area is } \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA$$

1114/1, 11-16, 19, 35

1114/3, 23, 39

## 17.7 Surface Integrals

$\iint_S f(x, y, z) dS$  as a Riemann Sum

For surface  $z = g(x, y)$ ,  $\iint_S f(x, y, z) dS = \iint_D f(x, y, g(x, y)) \sqrt{\frac{\partial z^2}{\partial x^2} + \frac{\partial z^2}{\partial y^2} + 1} dA$

In general,  $dS \rightarrow |\mathbf{r}_u \times \mathbf{r}_v| dA$

Surface integral of vector field  $\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S \mathbf{F} \cdot \mathbf{n} dS$ . Called flux of  $\mathbf{F}$  across  $S$ .

1127/5, 7, 19

1127/9, 11, 21

## 17.8 Stokes' Theorem

**Theorem 11** (Stokes' Theorem).  $\iint_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S} = \int_{\partial S} \mathbf{F} \cdot d\mathbf{r}$ .

1133/3, 7, 13

1133/5, 9, 17

## 17.9 Divergence Theorem

**Theorem 12** (Divergence Theorem).  $\iint_{\partial E} \mathbf{F} \cdot d\mathbf{S} = \iiint_E \nabla \cdot \mathbf{F} \, dV$ .

1139/1, 3, 7, 22

1139/5, 9, 23