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Depending linearly means that the objective function is in the form of a linear polynomial, a polynomial in which each of the variables occurs to the first power and none of the variables are multiplied together.

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The variables must also satisfy the *non-negativity condition*: they can't be negative.

The set of points, or values of the variables, which satisfy the constraints and the non-negativity condition is called the *feasible set*.

#### Theorem (Fundamental Theorem of Linear Programming)

The optimal value of the objective functions must occur at one of the vertices of the feasible set.

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If an extreme value occurs in a closed polygon, we easily see the extreme value must occur along the boundary, and then if it occurs along the boundary it must occur at one of the vertices, which is what the Fundamental Theorem of Linear Programming says. In a linear programming problem with just two variables and a handful of constraints, it's easy to sketch the feasible set and find its vertices.

Find the feasible set.

- Find the feasible set.
- Find the vertices.

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- ► Pick out the optimal value for the objective function.

We'll do some examples to help understand linear programming problems,

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We'll do some examples to help understand linear programming problems, but most linear programming problems that come up in real life involve numerous variables and constraints and e ectively require a more e cient approach. We'll do some examples to help understand linear programming problems, but most linear programming problems that come up in real life involve numerous variables and constraints and e ectively require a more e cient approach. The most common approach is called the *Simplex Method*.

Linear programming problems don't come out of thin air;

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The process of turning a real problem into a linear programming problem is the same involved in any other word problem:

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- Look for variables and unknowns.
- Find connections among the variables and unknowns. In this case, the connections translate into constraints along with the objective function.

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# In most word problems studied before, the connections translated to equations,

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In linear programming problems, we generally use the *Simplex Method*.

#### Consider the following maximum problem:

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Consider the following maximum problem:

$$2x + y \leq 3$$
  

$$3x + y \leq 4$$
  

$$x \geq 0, y \geq 0$$
  

$$p = 17x + 5y$$

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# The vertices of the feasible set and the values of the objective function p = 17x + 5y at those points are the following:

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$$\begin{array}{ccc} (0,0) & 0 \\ (4/3,0) & 22\frac{2}{3} \\ (1,1) & 22 \\ (0,3) & 15 \end{array}$$

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Thus, the maximum value for p is  $22\frac{2}{3}$ , which occurs at (4/3, 0).

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We will illustrate the Simplex Method using this example and then generalize the method so we can perform it mechanically, as an algorithm.

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The first step is to change the contraints from inequalities into equations by introducing what are called *slack variables*.

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Looking at the inequality  $2x + y \le 3$ , we introduce the slack variable u = 3 - (2x + y), so  $u \ge 0$  while 2x + y + u = 3.

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The first step is to change the contraints from inequalities into equations by introducing what are called *slack variables*. The slack variables essentially take up the slack in the inequalities.

Looking at the inequality  $2x + y \le 3$ , we introduce the slack variable u = 3 - (2x + y), so  $u \ge 0$  while 2x + y + u = 3.

Similarly, looking at the inequality  $3x + y \le 4$ , we introduce the slack variable v = 4 - (3x + y), so  $v \ge 0$  while 3x + y + v = 4.

We can thus restate the problem as

$$2x + y + u = 3$$
  

$$3x + y + v = 4$$
  

$$x, y, u, v \ge 0$$
  

$$p = 17x + 5y$$

where we find the maximum value for the objective function p which satisfies the contraints, now given as equations, and the non-negativity condition.

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If we rewrite the formula for the objective function in the form -17x - 5y + p = 0,

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$$2x + y + u = 3$$
  

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We will write down the augmented matrix for this system,

$$2x + y + u = 3$$
  

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We will write down the augmented matrix for this system, use it to easily pick out one of the vertices and the value of the objective function at that vertex, and then pivot in a way that will enable us to find another vertex at which the value for the objective function is larger.

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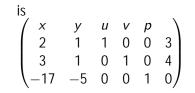
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The augmented matrix for the system

$$2x + y + u = 3$$
  

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$$-17x - 5y + p = 0.$$

is  

$$\begin{pmatrix} x & y & u & v & p \\ 2 & 1 & 1 & 0 & 0 & 3 \\ 3 & 1 & 0 & 1 & 0 & 4 \\ -17 & -5 & 0 & 0 & 1 & 0 \end{pmatrix}$$

The first row isn't actually part of the augmented matrix, but we'll write it down as a reminder of which variable each column is associated with.

$$\begin{pmatrix} x & y & u & v & p \\ 2 & 1 & 1 & 0 & 0 & 3 \\ 3 & 1 & 0 & 1 & 0 & 4 \\ -17 & -5 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Looking at the matrix, it's fairly obvious that the columns corresponding to x and y are the most complicated.

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So we have a solution of the equations giving x = 0, y = 0, u = 3, v = 4 and p = 0.

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We will call x and y Group I variables and we will call u and v Group II variables.

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Each time we pivot, we will exchange one pair of variables, one from Group I and one from Group II, to get another set of Group I variables which will be set to 0.

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We will call x and y Group I variables and we will call u and v Group II variables.

Each time we pivot, we will exchange one pair of variables, one from Group I and one from Group II, to get another set of Group I variables which will be set to 0. This will give another fairly obvious solution, which will correspond to another vertex and another value of the objective function.

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The last row gives a formula -17x - 5y + p = 0 involving the objective function.

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The last row gives a formula -17x - 5y + p = 0 involving the objective function. We can solve this for the objective function, getting p = 17x + 5y.

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We'll do this by pivoting about the column corresponding to  $x_i$ ,

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We'll do this by pivoting about the column corresponding to x, in other words, we'll pivot about the first column.

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We now have to decide which entry in the first column to pivot around.

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If we pivoted about the first row, we'd start by dividing the first row by 2, getting 3/2 in the last column.

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#### The Pivot

$$\begin{pmatrix} 2 & 1 & 1 & 0 & 0 & 3 \\ 3 & 1 & 0 & 1 & 0 & 4 \\ -17 & -5 & 0 & 0 & 1 & 0 \end{pmatrix}$$
  
First, we divide the second row by 3 to get a 1 at the pivot point:  
$$\begin{pmatrix} 2 & 1 & 1 & 0 & 0 & 3 \\ 1 & 1/3 & 0 & 1/3 & 0 & 4/3 \\ -17 & -5 & 0 & 0 & 1 & 0 \end{pmatrix}$$

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#### The Pivot

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To get 0's elsewhere in the first column, we'll subtract 2× the pivot row from the first row and add 17× the pivot row to the third row:  $R_1 \leftarrow R_1 - 2R_2, R_3 = R_3 + 17R_2$ :  $\begin{pmatrix} 0 & 1/3 & 1 & -2/3 & 0 & 1/3 \\ 1 & 1/3 & 0 & 1/3 & 0 & 4/3 \\ 0 & 2/3 & 0 & 17/3 & 1 & 68/3 \end{pmatrix}$ 

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We'll rewrite the matrix with the columns again labeled:

$$\begin{pmatrix} x & y & u & v & p \\ 0 & 1/3 & 1 & -2/3 & 0 & 1/3 \\ 1 & 1/3 & 0 & 1/3 & 0 & 4/3 \\ 0 & 2/3 & 0 & 17/3 & 1 & 68/3 \end{pmatrix}$$

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This time, the Group II variables are y and v and we'll set them to 0.

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We can then interpret the equations. The first row corresponds to the equation  $\frac{1}{3}y + u - \frac{2}{3}v = \frac{1}{3}$ .

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We can then interpret the equations. The first row corresponds to the equation  $\frac{1}{3}y + u - \frac{2}{3}v = \frac{1}{3}$ . Since y = v = 0, we get  $u = \frac{1}{3}$ .

We'll rewrite the matrix with the columns again labeled:

$$\begin{pmatrix} x & y & u & v & p \\ 0 & 1/3 & 1 & -2/3 & 0 & 1/3 \\ 1 & 1/3 & 0 & 1/3 & 0 & 4/3 \\ 0 & 2/3 & 0 & 17/3 & 1 & 68/3 \end{pmatrix}$$

This time, the Group II variables are y and v and we'll set them to 0.

We can then interpret the equations. The first row corresponds to the equation  $\frac{1}{3}y + u - \frac{2}{3}v = \frac{1}{3}$ . Since y = v = 0, we get  $u = \frac{1}{3}$ . The second row corresponds to the equation  $x + \frac{1}{3}y + \frac{1}{3}v = \frac{4}{3}$ .

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This corresponds to the vertex (4/3, 0), giving the value  $\frac{68}{3} = 22\frac{2}{3}$  for the objective function.

Looking at the last row, corresponding to the equation  $\frac{2}{3}y + \frac{17}{3}v + p = \frac{68}{3}$ , more closely, we can solve for *p* to get:

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We just found a vertex corresponding to values of 0 for y and v.

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We just found a vertex corresponding to values of 0 for y and v. Any other solution would either involve still having 0 values for yand v, which would give the same value for p,

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We just found a vertex corresponding to values of 0 for y and v. Any other solution would either involve still having 0 values for yand v, which would give the same value for p, or would involve positive values for one or both of y and v, which would give a smaller value for p.

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Looking at the last row, corresponding to the equation  $\frac{2}{3}y + \frac{17}{3}v + p = \frac{68}{3}$ , more closely, we can solve for p to get:  $p = \frac{68}{3} - \frac{2}{3}y - \frac{17}{3}v$ .

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We'll analyze what we just did, synthesize it, and come up with the *Simplex Method*.

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- 2. We also rewrite the formula for the objective function, bringing all the variables over to the left side.
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- 2. We also rewrite the formula for the objective function, bringing all the variables over to the left side.
- 3. We now write down the augmented matrix for the system of equations, with the folowing optional adjustment: Since we never pivot about the last row, the next to last column never changes. E ectively, the next to last column is unnecessary, so we don't have to write it down.

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At this point, we have the Initial Simplex Tableau.

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Once we have chosen the pivot row and pivot column, we pivot.

## We continue pivoting until we can't pivot any more,

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At this point, we can set the Group I variables to 0, easily find the values for the Group II variables, and the entry in the bottom right of the matrix will be the value of the objective function.

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If the inequality goes the other way, we can deal with it by multiplying both sides by -1.

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If the inequality goes the other way, we can deal with it by multiplying both sides by  $-1.\,$  In other words, if we have an equality of the form

 $P \geq k$ ,

where P is a linear polynomial and k is a constant, we can instead use the equivalent inequality

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The complication is that this is likely to lead to a negative number on the right hand side. We need to see how to deal with that.

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The problem with having a negative constant is that when we pick out what we hope will be a feasible solution, one of the variables will fail to satisfy the non-negativity condition.

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The problem with having a negative constant is that when we pick out what we hope will be a feasible solution, one of the variables will fail to satisfy the non-negativity condition. We deal with that via some preliminary pivoting on the Initial Simplex Tableau.

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- If there is more than one row with a negative entry in the last column, we can look at any of those rows.
- If there is more than one negative entry in that row, we may choose any of the columns with a negative entry as the pivot column.

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Once we have the pivot column, we choose the pivot row in the usual way, with the following adjustment:

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We then pivot

We then pivot and repeat this preliminary process until there are no more negative entries in the last column.

We then pivot and repeat this preliminary process until there are no more negative entries in the last column. At that point, we proceed with the Simplex Method in the usual way.

## We minimize the objective function by maximizing its additive inverse,

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We minimize the objective function by maximizing its additive inverse, that is, its negative.

In other words, if we need to minimize p, we simply maximize M = -p.

When we are finished pivoting, we then merely recognize that the entry in the lower right hand corner of the final simplex tableau is the negative of minimum value for the objective function.

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