Solving Systems of Linear Equations

There are two basic methods we will use to solve systems of linear equations:

- Substitution
- Elimination

We will describe each for a system of two equations in two unknowns, but each works for systems with more equations and more unknowns.

So assume we have a system of the form:

$$ax + by = c$$
$$dx + ey = f$$

Substitution

To use substitution, we solve for one of the variables in one of the equations in terms of the other variable and substitute that value in the other equation.

That gives us a single equation in one variable, which we may solve and then substitute that solution into either original equation or, even better, into the formula we got for the other variable.

Elimination

With elimination, we *legally* modify the equations so that, for one variable, its coefficients in the two equations match up, being either the same or negatives of one another.

When the coefficients match up, we either add or subtract, meaning we equate either the sum or difference of the left sides of the two equations together with the sum or difference of the right sides of the two equations.

Elimination

For example, given the equations

$$(1) ax + by = c$$

dx + ey = f,

we might multiply both sides of (1) by d to get

$$(3) adx + bdy = cd$$

and multiply both sides of (2) by a to get

$$(4) adx + aey = af.$$

Elimination

Since the coefficients of x are the same, we equate the differences of the two sides, getting

(5)
$$(bd - ae)y = cd - af.$$

We can then solve (5) by dividing both sides by bd - ae to get $y = \frac{cd - af}{d}$.

 $\overline{bd-ae}$

We can then either plug this value into any of the equations, or perform a similar calculation to eliminate y and solve for x.

Example

Solve

$$2x + 5y = 16$$
$$3x + 2y = 13$$

We might multiply both sides of the first equation by 3 and the second by 2, getting

$$6x + 15y = 48$$

 $6x + 4y = 26.$

Subtracting, we get 11y = 22, y = 2.

We can substitute that into the first equation to get $2x + 5 \cdot 2 = 16$, 2x + 10 = 16, 2x = 6, x = 3.

Steps We May Take to Solve Equations

Every step taken to solve an equation or a system of equations may be categorized as one of the following.

- Adding the same thing to both sides of an equation.
- Subtracting the same thing from both sides of an equation.
- Multiplying both sides of an equation by the same non-zero thing.
- Dividing both sides of an equation by the same non-zero thing.
- Replacing something by something else equal to it.
- Raising both sides of an equation to the same power. Beware that this step may introduce extraneous solutions.

Elementary Operations on Systems of Linear Equations

We will come up with a mechanical method for solving systems of linear equations called Gaussian Elimination. It will not always be the most efficient way when solving equations by hand, but will be an excellent way to instruct a computer to use and will also lead to greater understanding of the Simplex Method for solving linear programming problems.

We will first reduce the steps we take to solve equations to just three and see how these suffice for solving systems of linear equations. We will use slang to denote these steps; it's important to recognize what we really mean.

The Three Elementary Row Operations

- (1) Multiply an equation by a non-zero constant. Obviously, this is something that should not be taken literally. What's really meant is to multiply both sides of an equation by the same non-zero constant to obtain a new equation equivalent to the original equation.
- (2) Add a multiple of one equation to another. Again, this should not be taken literally. It really means to add a multiple of the left side of one equation to the left side of another and also add the same multiple of the right side of that equation to the right side of the other.
- (3) Interchange two equations. This is obviously legitimate but may seem pointless. It is essentially pointless if solving equations by hand but will not be pointless when instructing a computer to solve a system of equations.

Elementary Row Operations on Matrices

When solving equations using elimination, the variables themselves are almost superfluous. One could change the names of the variables and perform exactly the same steps, or even just write down the coefficients, do arithmetic using the coefficients, and interpret the results.

When we write down the coefficients in an organized, rectangular array, we get something called a *matrix*. A matrix is simply a rectangular array of numbers.

Consider the following example, where we solve a system of two equations in two unknowns, simultaneously performing analogous operations on the coefficients.

Example

 $3x + y = 11 \qquad \begin{pmatrix} 3 & 1 & 11 \\ x - y = -3 & \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & -3 \end{pmatrix}$

We'll now add the second equation to the first to eliminate y from the first equation. Simultaneously, we'll add each of the coefficients in the second row to the coefficients in the first row.

 $\begin{array}{rrrr} 4x = 8 & & \begin{pmatrix} 4 & 0 & 8 \\ x - y = -3 & & \begin{pmatrix} 1 & -1 & -3 \end{pmatrix} \end{array}$

Now we'll divide both sides of the first equation by 4 and simultaneously divide the coefficients in the first row of the matrix to the right by 4.

$$\begin{aligned} x &= 2 \\ x - y &= -3 \end{aligned} \begin{pmatrix} 1 & 0 & 2 \\ 1 & -1 & -3 \end{pmatrix} \\ & & \text{Example} \end{aligned}$$

Now we can eliminate x from the second equation by subtracting the first from the second. Simultaneously, we will subtract the coefficients in the first row of the matrix from the coefficients in the second row.

$$\begin{array}{ccc}
x = 2 & & \begin{pmatrix} 1 & 0 & 2 \\ 0 & -1 & -5 \end{pmatrix} \\
\end{array}$$

Finally, we'll multiply the second equation by -1 and simultaneously multiply the coefficients in the second row of the matrix by -1.

$$\begin{array}{l} x = 2 \\ y = 5 \end{array} \quad \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 5 \end{pmatrix}$$

We can read off the solution to the system from the matrix as well as from the equations.

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Elementary Row Operations on Matrices
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The three elementary operations we earlier stated for systems of linear equations translate as follows to elementary row operations on matrices.

- Multiply a row by a non-zero constant. By this, we really mean to multiply every element of a row by the same non-zero constant. We can also divide a row by a non-zero constant, since division is a form of multiplication.
- Add a multiple of one row to another. By this, we really mean to take a multiple of each element of one row and add it to the corresponding element of another row. We can also subtract a multiple of one row from another, since subtraction is a form of addition.
- Interchange two rows.

Matrices - Terminology and Notation

A matrix is simply a rectangular array of numbers. It corresponds to a two-dimensional array in just about any computer language. A spreadsheet can be viewed as a large matrix. Newspapers make extensive use of matrices, from box scores and standings in the sports pages to the stock listings in the financial section.

A matrix has rows and columns; the rows go across, from left to right and the columns go vertically, up and down.

We often refer to a matrix via a capital letter, such as A, and we may write $A_{r\times c}$ to indicate the matrix has r rows and c columns.

The entry in the i^{th} row and j^{th} column of a matrix A is referred to as $a_{i,j}$, and we sometimes write $A = (a_{i,j})$.

A matrix is generally enclosed in a large pair of parentheses.

The Augmented Matrix

Every system of linear equations has a corresponding *augmented matrix*. We get the augmented matrix by writing down the coefficients of each equation in order in a row and then writing the constant from the write side of the equation at the end of the row. Be careful that zero coefficients are included.

A system of m equations with n unknowns will yield an $m \times n + 1$ matrix, that is, a matrix with m rows and n + 1 columns.

Pivoting

A key process both in solving systems of equations and in solving linear programming problems using the Simplex Method is called *pivoting*. We pivot about a given entry in a given row and column. Pivoting is a two-step process, hence the term.

Suppose we wish to pivot about the entry in the i^{th} row, j^{th} column.

- Step 1: Divide the i^{th} row by $a_{i,j}$, the entry in the i^{th} row, j^{th} column. The gives a new matrix with a 1 in the i^{th} row, j^{th} column.
- Step 2: For every other row, let k be the element in the j^{th} column of that row. Subtract k times the i^{th} row from that row. That will put a 0 in every row in the j^{th} column except for the i^{th} row.

Example

Pivot about the second row, third column of the matrix $\begin{pmatrix} 5 & 3 & 7 \\ 6 & 4 & 2 \\ 2 & 7 & 5 \end{pmatrix}$.

Step 1: Divide the second row by 2 to get:
$$\begin{pmatrix} 5 & 3 & 7 \\ 3 & 2 & 1 \\ 2 & 7 & 5 \end{pmatrix}$$
.

Step 2: First subtract 7 times the second row from the first row to get:

 $\begin{pmatrix} -16 & -11 & 0 \\ 3 & 2 & 1 \\ 2 & 7 & 5 \end{pmatrix}$, and then subtract 5 times the second row from the

third row to get:
$$\begin{pmatrix} -16 & -11 & 0 \\ 3 & 2 & 1 \\ -13 & -3 & 0 \end{pmatrix}$$
.

Gaussian Elimination

The method of Gaussian Elimination amounts to repeatedly applying the Pivot Method to the augmented matrix of a system of equations until the solution is obvious.

- We start by pivoting about the entry in the first row, first column. If the entry in that place is 0, we first interchange the first row with another row with a non-zero entry in the first column and then pivot.
- After we pivot about a given row and column, we go down one row and to the right one column and pivot about that entry if it's not 0. If that entry is 0, we first interchange that row with some row below it with a non-zero entry in that column and then pivot. If there is no non-zero entry further down in that column, we go over one row to the right and try to pivot there.
- We continue until we reach the lower right hand corner.