

**Computability Theory and the Game Cops and  
Robbers on Graphs**

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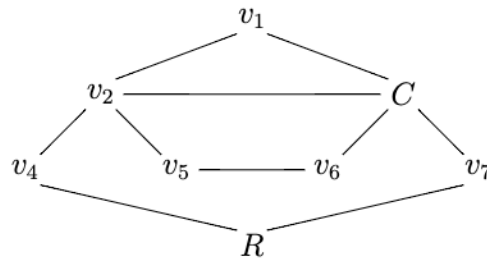
## **Acknowledgements**

I would like to thank my thesis advisor, Dr. Reed Solomon, for his patience and guidance throughout my research process. Not only has he helped me learn more about graph and computability theory, he has served as a great role model and advisor.

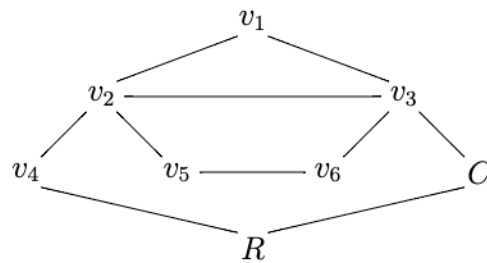
## Introduction

Do you remember playing the game "cops and robbers" as a child? Now, imagine the game on graphs. Every player can only move one space for each of their turns. We can see the game being played below. We will use a  $R$  to represent the robber and a  $C$  to represent the cop.

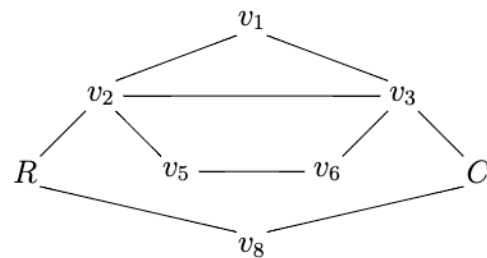
Start Positions:



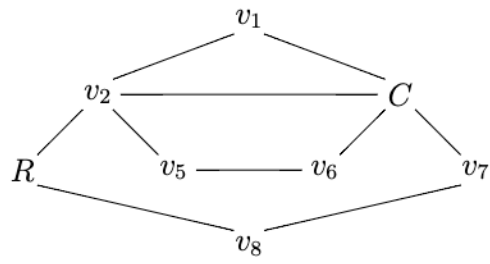
Cop's First Move:



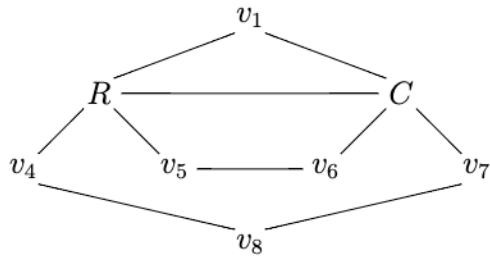
Robbers' First Move:



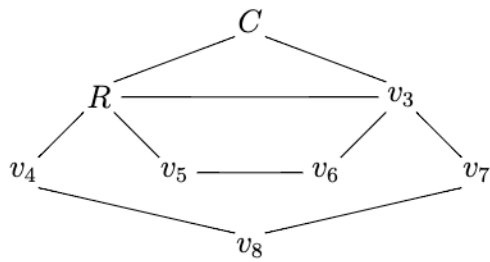
Cop's Second Move:



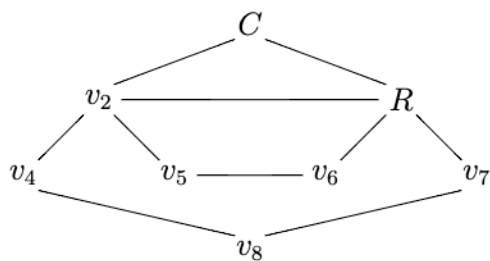
Robbers' Second Move:



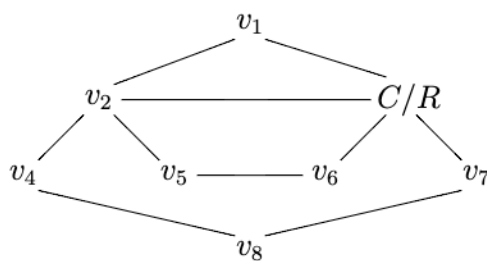
Cop's Third Move:



Robbers' Third Move:



Cop's Third Move:



We can see that the cop wins at this point because it is on the same point as the robber. The robber could have better avoided the cop by moving to  $v_5$  instead of  $v_3$  on his third move. In some graphs, the robber can always win if he plays with a particular strategy. We call these graphs robber-win. Graphs that can always be won by the cop if she plays correctly are called cop-win. We can also play with multiple cops. The cop number is the minimum number of cops required to win on a graph for any way the robber moves.

We can consider programs that determine the way a cop moves. These programs can be thought of as a cop's strategy. Rachel Stahl found a computable cop-win graph such that no cop strategy is computable. In this paper, we will find a computable cop-win graph such that no there is computable strategy to win for  $n$ -cops and infinitely many cops.

### Introducing Graphs

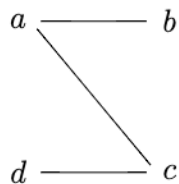
**Definition:** A graph  $G$  consists of

- (1) A nonempty set of vertices, which we will denote  $V(G)$
- (2) A binary edge relation on  $V(G)$ , denoted by  $E(G)$

We will denote an edge from vertex  $x_1$  to vertex  $x_2$  by  $(x_1, x_2)$ . One can see from this notation then that  $E(G) \subseteq V(G) \times V(G)$ . A graph  $G$  is reflexive if for each

vertex  $x \in V(G)$ , an edge from  $x$  to  $x$  exists or that  $(x, x) \in E(G)$ . A graph  $G$  is undirected if  $E(G)$  is symmetric, meaning that if  $(x, y) \in E(G)$  for  $x, y \in V(G)$ , then  $(y, x) \in E(G)$ . In this case, we can say that  $(x, y) = (y, x)$ . If a graph is directed, meaning that  $(x, y) \in E(G)$  does not imply  $(y, x) \in E(G)$ , there will be an arrow on the edges showing their direction. For the purposes of this paper, we will be working with only reflexive and undirected graphs.

**Example:** Let  $G_1$  be the graph shown below. It consists consists of the vertex set  $V(G_1) = \{a, b, c, d\}$ . For ease of notation, we will list only the nonreflexive and one from each pair of symmetric edges. Thus, the edge set is  $E(G_1) = \{(a, b), (a, c), (c, d)\}$ .

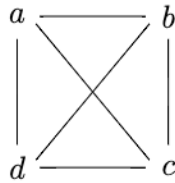


$G_1$

The index of a vertex  $x$  in a graph  $G$  is the number of distinct edges  $(x, y)$  where  $y \in V(G)$  and  $x \neq y$ . For example, in the graph shown above, the index of vertex  $a$  is 2. For  $x, y \in V(G)$ , we say  $x$  and  $y$  are neighbors if  $(x, y) \in E(G)$ .

For  $x_1, x_n \in V(G)$ , a walk from  $x_1$  to  $x_n$  is an ordered set of vertices  $(x_1, x_2, \dots, x_n)$  such that any two consecutive vertices are adjacent. For  $x_1, x_n \in V(G)$ , a path from  $x_1$  to  $x_n$  is walk from  $x_1$  to  $x_n$  such that no vertex appears twice. We will denote this as an  $(x_1, x_n)$ -path. We can notice that all paths are walks, but not all walks are paths.

**Example:** In  $G_2$  shown below, an example of a walk is  $(a, c, d, c, b)$  and an example of a path is  $(a, b, c, d)$ .

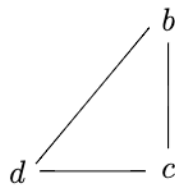


$G_2$

The length of a path is the number of edges it uses. In  $G_2$ , the path  $(a, b, c, d)$  has a length of 3. The distance between two points  $x, y \in G$  is the length of the shortest  $(x, y)$ -path. In  $G_2$ , the distance between any two distinct vertices is 1.

**Definition:** A subgraph  $H$  of  $G$  is a graph such that  $V(H) \subseteq V(G)$  and  $E(H) \subseteq E(G)$ . For example,  $G_1$  is a subgraph of  $G_2$ . An induced subgraph  $H$  of  $G$  is a subgraph of  $G$  such that if  $u, v \in V(H)$  and  $(u, v) \in E(G)$ , then  $(u, v) \in H$ .

For  $v \in V(G)$ , we define  $G - \{v\}$  to be the induced subgraph of  $G$  with all points in  $G$  except for  $v$ . In other words,  $v$  and all of its edges are taken out of  $G$ . For example,  $G_2 - \{a\}$  is shown below.



$G_2 - \{a\}$

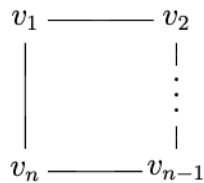
### Types of Graphs

We will be working with both infinite and finite graphs. If a graph  $G$  is infinite, the vertex set  $V(G)$  is of infinite size. A graph  $G$  is locally finite if the index of every point is finite. We note that infinite graphs can be locally finite and that all finite graphs are locally finite.

A straight line path of length  $n$  is a finite graph with  $n$  vertices such that  $n - 2$  of the vertices have an index of 2 and the 2 end vertices have an index of 1. These graphs are of the form shown below.

$$v_1 - v_2 - v_3 - \cdots - v_n$$

A circle or cycle of length  $n$  is a finite graph with  $n$  vertices such that each vertex is of index 2. By relabeling, these graphs can be depicted as follows.



**Definition:** If for all  $x, y \in V(G)$ ,  $(x, y) \in E(G)$ , we call  $G$  a complete graph. In other words, for a complete graph  $G$ ,  $E(G) = V(G) \times V(G)$ .

**Corollary:** *If a graph  $G$  is locally finite and complete, then it must be a finite graph.*

*Proof.* Suppose for the purpose of contradiction that  $G$  is infinite. Since  $G$  is complete,  $x \in V(G)$  must share an edge with all other points in  $G$ . Since  $G$  is infinite, this would mean  $x$  shares an edge with infinitely many points. Thus,  $x$  does not have a finite index, which contradicts  $G$  being locally finite. Therefore,  $G$  must be finite.

□



An infinite ray, shown below, is an infinite graph where exactly 1 point has an index of 1 and all of the other points have an index of 2.

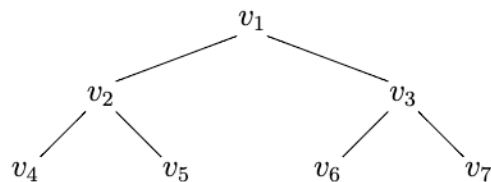
$$v_1 - v_2 - v_3 - \dots$$

An infinite 2-way ray, shown below, consists of infinitely many points, all with an index of 2.

$$\dots - v_1 - v_2 - v_3 - \dots$$

**Definition:** A graph  $G$  is connected if for all  $x, y \in V(G)$ , there exists a path from  $x$  to  $y$ . A cut vertex is a vertex  $v \in v(G)$  such that  $G - \{v\}$  is not connected.

A tree is a connected graph  $G$  where no subgraph is a cycle. These can be infinite or finite. A tree is shown below.



In the tree graph above, we can see that  $v_1$ ,  $v_2$ , and  $v_3$  are all cut vertices, but  $v_4$ ,  $v_5$ ,  $v_6$ , and  $v_7$  are not cut vertices.

### The Game of Cops of Robbers

The game of cops and robbers consists of  $n + 1$  players for some positive integer  $n$  where there are  $n$  cops and 1 robber. To start, we will learn about the rules of the game when there is only 1 cop on a graph  $G$ .

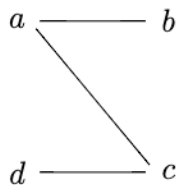
### Game Procedure:

- (1) The cop picks a vertex in  $G$  to start
- (2) The robber picks a vertex in  $G$  to start
- (3) The players take turns moving from their current vertex to any neighbor of the vertex.

Since  $G$  is assumed to be undirected and reflexive, the players can move along edges in any direction and use their turn to remain at their current vertex.

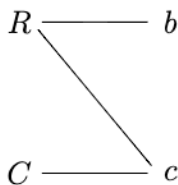
A cop wins the game if she moves onto the same vertex as the robber. The robber wins the game if the cop never moves onto the same vertex as him.

**Example:** We can show the game on graph  $G_1$ , shown below.

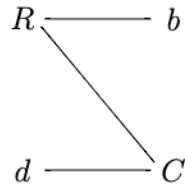


Now, we will represent the placement of the robber with  $R$  and that of the cop with  $C$ .

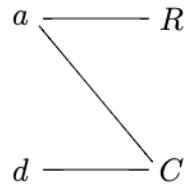
Start positions:



Cop's first move:

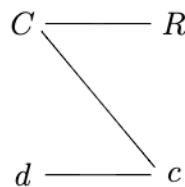


Robber's first move:



For the robber's second move, he will stay at vertex  $b$ , so we are now onto the cop's move.

Cop's second move:

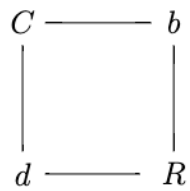


From this point, the cop can win because the robber has nowhere to go and the cop is at neighbor of the robber's location.

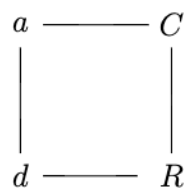
For any graph  $G$ , either the cop can win if she plays carefully no matter what the robber does or the robber can win if he plays carefully no matter what the cop does. With this information, we classify a graph as either being cop-win or robber-win. A graph that can be won by the cop no matter how the robber plays is classified as cop-win. A graph that can be won by the robber no matter how the cop plays is classified as robber-win.

**Example:** We can see that the 4-cycle graph below is robber win because the robber can always move to stay 2 places further from the cop.

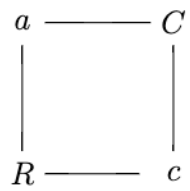
Start Position:



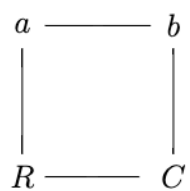
Cop's First Move:



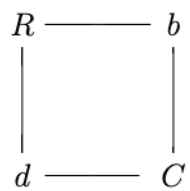
Robber's First Move:



Cop's Second Move:



Robber's Second Move:



We can see how this pattern can continue and how the robber can always move to stay 2 edges away from the cop.

Similarly, for any integer  $n \geq 4$ , an  $n$ -cycle graph is robber win. We can also see that if a graph is disconnected, it is automatically robber-win because the robber can start the game at a node disconnected from the cop's start position. Then, there is no path between the cop and robber, so there is no possible way for the cop to win. Since it is clear that all disconnected graphs are robber-win, we will only be focused on studying connected graphs.

Although the cop can start from any position, designating a start position does not change the nature of the game. Suppose that we designate a start position,  $v_0$ . Since we can assume the graph is connected, there must exist a  $(v_0, v)$ -path for any other vertex  $v$  in the graph. Thus, the cop can move to  $v$  in her first several moves. Thus, the game is not changed by designating a start position for the cop.

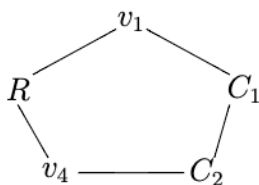
### Cops of Robbers With Multiple Cops

The game can also be played with more than 1 cop. Similar to the original game, every player starts at a vertex and takes turns moving to neighboring vertices of their original vertices.

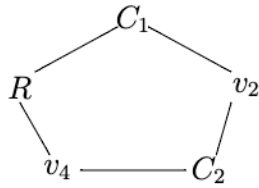
**Definition:** For a finite graph  $G$ , the cop number of  $G$  is the least number of cops required to make  $G$  cop-win.

**Example:** We can see that a 4-cycle graph has a cop number of 2.

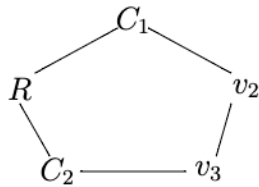
Start Position:



Cop 1's First Move:



Cop 2's First Move:



Then, we can see that the robber is cornered and Cop 1 can win on her next turn. Similarly, any  $n$ -cycle graph for any integer  $n \geq 4$  has a cop number of 2 because the cops can close in on the robber from both sides. We can also see that the cops can start from a fixed vertex because they can still use their moves to close in on the robber.

## Computability Theory

Computers use a program and an input of information to either give an output or to never stop running and not give any information. We can think of a computer as a function  $U$  which has the input of a computer program  $e$  and an input  $x \in \mathbf{N}$ . Then, the function will either give an output  $y \in \mathbf{N}$  or it will diverge, meaning that it will run forever. This function is shown below.

$$U(e, x) \mapsto \begin{cases} y & \text{if the function halts} \\ \text{diverges} & \text{if the function never halts} \end{cases}$$

We can also write this function as  $\Phi_e(x)$  where  $e$  represents the program code and  $x$  represents the input. Each function  $\Phi_e$  is called partial computable because it might diverge on some inputs. A computable function  $\Phi_e$  converges (i.e. gives an output) on all inputs.

We can assume that  $\varphi_e$  works on finite sequences as well as numbers. We can use the labels  $V(G) = \{v_1, v_2, \dots, v_n\}$  to describe how players in the game of cops and robbers move. For example, the sequence  $\langle 3, 5, 6, 2, 4, 3 \rangle$  indicates that the cop started on  $v_3$  while the robber started on  $v_5$ . Then, the cop moved to  $v_6$  and the robber moved to  $v_2$ . For her third turn, the cop moved to  $v_4$ . For his third turn, the robber stayed at  $v_2$ . For the game to be played in this manner, we can see that edges  $(v_3, v_6)$ ,  $(v_4, v_6)$ , and  $(v_2, v_5)$  must all exist.

## Computability Findings

### Computability With Finitely Many Cops

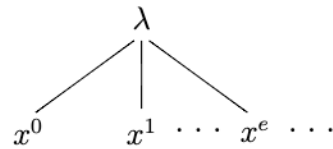
A cop strategy on a graph  $G$  is a function  $f : \mathbf{N} \times \mathbf{N} \times \mathbf{N} \rightarrow \mathbf{N}$  that tells the cop how to move. We can let  $\sigma$  represent the sequence of moves coded by a natural number that tells us how the players have moved thus far. Then, we can say the cop's current position is at  $v_i$  and the robber is at  $v_j$ . Then,  $f(\sigma, v_i, v_j)$  is the index of where the cop should move to. If the output of  $f$  describes a legal move in the game then it is a cop strategy. If  $f$  is a total computable function, then we say it is a computable cop strategy.

We can also define a cop strategy for  $n$ -cops similarly. We can have a function  $f : \mathbf{N}^{n+2} \rightarrow \mathbf{N}$ . Let  $\sigma$  represent the history of moves of the players thus far,

$c_1, \dots, c_n$  be the locations of the cops and let  $r$  be the location of the robber. Then,  $f(\sigma, c_1, \dots, c_n, r) = (\hat{c}_1, \dots, \hat{c}_n)$  tells us that cop  $i$  should move from  $c_i$  to  $\hat{c}_i$  on this turn. If the output of  $f$  describes legal moves in the game, then it is a  $n$ -cop strategy. If  $f$  is a total computable function, then we say it is a computable  $n$ -cop strategy.

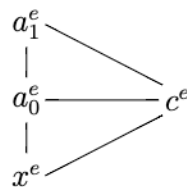
**Theorem:** *There exists a computable graph  $G$  that can be won with  $n$  computable cops, such that no winning strategy exists with  $n - 1$  computable cops and 1 non-computable cop can win.*

*Proof.* To start,  $G$  will consist of a root node  $\lambda$  and have infinitely many countable sections for the graph. We can assume that the cops start on the  $\lambda$  node. We will defeat each computable function  $\Phi_e$  as a computable  $n - 1$  cop strategy.



We will expand  $G$  by building subgraphs off of each node  $x^e$ . These subgraphs will be called the  $e$ -sections of graph and are disjoint. The  $e$ -section of the graph can only be accessed through the  $x^e$  node, so each  $x^e$  is a cut vertex.

Each  $e$ -section of the graph should start with the following configuration. We can let the robber start at the node  $a_1^e$  for some  $e$ -section of the graph.

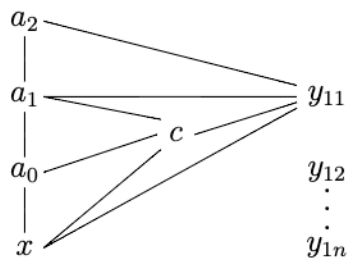




We will build the e-section of the graph by simulating how the partial computable function  $\Phi_e$  controls the  $n - 1$  cops when the robber starts at  $a_1^e$ . The function  $\Phi_e$  uses the positions of the robber and the cops to give an output telling where to move the  $n - 1$  cops. If  $\Phi_e$  moves the  $n - 1$  cops into a position from which they could win in the next round, meaning that the cops are moved to a node which is a neighbor of the node that robber is at, we will expand the e-section to give the robber an escape route. This escape route will be built in such a way that  $n$  computable cops can win and 1 non-computable cop can win.

### Expanding the E-Section

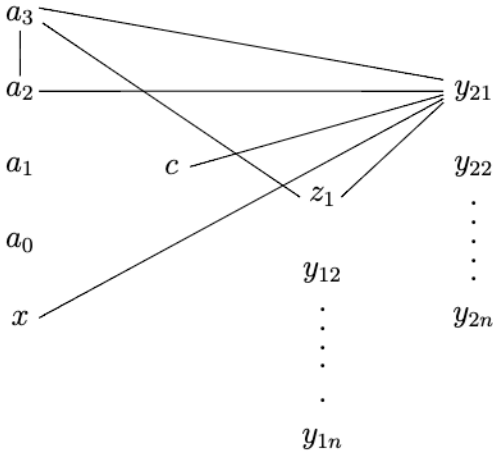
For ease of notation, we will drop the superscript on all points in the “e-section” of the graph throughout the construction of the graph. Consider  $\Phi_e$  acting on the initial cop position  $\lambda$  and the initial robber position at  $a_1$ . We check if  $\Phi_e$  moves a cop to a neighbor of  $a_1$ . Thus, we continue to watch  $\Phi_e$  while keeping the robber at  $a_1$  until a cop is moved to either  $a_0$  or  $c$ . If not, we take no action for  $\Phi_e$ . If so, we add vertices  $a_2, y_{11}, y_{12}, \dots, y_{1n}$  with connections from  $a_2$  and  $y_{11}$  shown below.



We add edges from each  $y_{1i}$  in a symmetric way. For all  $i \in \{1, \dots, n\}$ ,  $y_{1i}$  is connected to  $a_1$ ,  $a_2$ ,  $x_e$ , and  $c$ , but we will only show the connections to  $y_{11}$  for simplification. If we have  $j \neq i$ , then  $y_{1i}$  is not connected to  $y_{1j}$ .

After expanding  $G$ , we return to computing  $\Phi_e$  to simulate how it would move the cops. At least one of the cops just moved to either  $a_0$  or  $c$  while the robber is at  $a_1$ . The robber will move to  $a_2$ . Continue to compute the trajectory of the the cops. If the cops do not move within one space of the robber, the robber should stay at  $a_2$ .

If a cop does move within one space of the robber, to either  $a_1$ ,  $y_{11}, y_{12}, \dots, y_{1n}$ , then we will expand the graph by adding vertices  $a_3, y_{21}, y_{22}, \dots, y_{2n}$ . Since  $\Phi_e$  only controls  $n - 1$  cops, we know that at least one  $y_{1i}$  does not have a cop at it. We will name this point  $z_1$ . Since  $y_{1i}$  is symmetric, we can assume without loss of generality that  $y_{11} = z_1$ . Then, the graph will be expanded with edges shown for  $y_{21}$ . For clarity, we will only show the new edges.

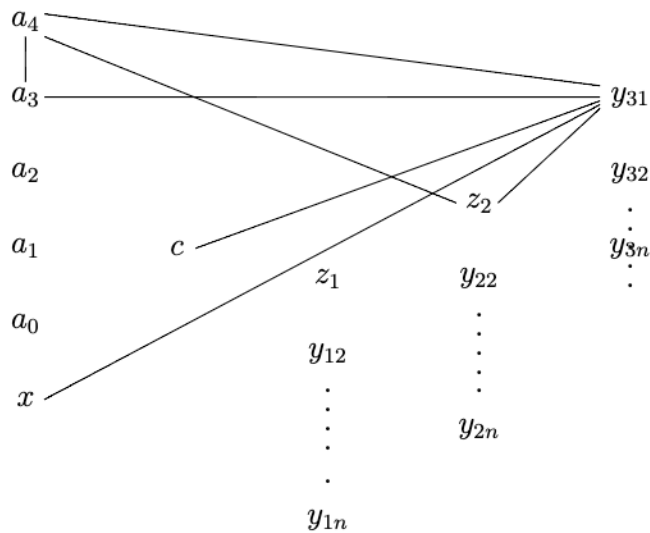


Once again, we add edges so each  $y_{2i}$  is symmetric. For all  $i \in \{1, \dots, n\}$ ,  $y_{2i}$  is connected to  $a_2$ ,  $a_3$ ,  $c$ ,  $z_1$ , and  $x_e$ . We also have that if  $y_{1i} = z_1$ ,  $y_{1i}$  is connected to  $a_3$  and if  $i \neq j$ , then  $y_{1j}$  is not connected to  $a_3$ .

After expanding  $G$ , we continue computing  $\Phi_e$  to simulate the game. Recall that  $\Phi_e$  moved at least one cop to either some  $y_{1i} \neq z_1$  or  $a_1$ . We move the robber to

$a_3$  and continue to compute  $\Phi_e$ . Then, the closest cop must be two spaces from the robber because  $a_3$  is only connected to  $a_2$  and  $z_1 \neq y_{1i}$ , if a cop is at  $y_{1i}$ .

We leave the robber at  $a_3$  until a cop moves within one space of the robber. Suppose that a cop does move within one space of the robber. This would mean that a cop moved to either  $z_1$ ,  $a_2$ , or  $y_{2i}$  for  $i = 1, 2, \dots, n$ . There must be at least one  $y_{2i}$  that does not have a cop at it. We will call this point  $z_2$ . Without loss of generality, assume that  $y_{21} = z_2$ . We will expand the graph by adding  $y_{31}, \dots, y_{3n}$ , and  $a_4$  as follows. Once again, we will only show the new edges and the connections to  $y_{31}$  represent all the connections to every  $y_{3i}$ .



For all  $i \in \{1, \dots, n\}$ ,  $y_{3i}$  is connected to  $a_3$ ,  $a_4$ ,  $c$ ,  $z_2$ , and  $x$ . We also have that  $z_2$  is connected to  $a_4$ , but no other node of the form  $y_{2j}$  is connected to  $a_4$ .

In general, for  $k \in \mathbf{N}$ ,  $a_{k+1}$  is connected to  $a_k$ ,  $z_{k-1}$ , and  $y_{ki}$  for all  $i = 1, 2, \dots, n$ . The robber stays at  $a_{k+1}$ . If  $\Phi_e$  moves a cop to  $a_k$ ,  $z_{k-1}$ , or  $y_{ki}$ , the graph is expanded by adding  $a_{k+2}$  and  $y_{k+1,i}$ . We set  $z_k$  to be the a node of the form  $y_{ki}$  that does not

have a cop. We add edges from  $a_{k+1}$  and  $z_k$  to  $a_{k+2}$ . We build an edge from each  $y_{k+1,i}$  to  $a_{k+1}$ ,  $a_{k+2}$ ,  $c$ ,  $x$ , and  $z_k$ .

In the end, the e-section will either be finite or infinite. If the e-section is finite, it will consist of  $x$ ,  $c$ ,  $a_0$ ,  $a_1$ ,  $a_{i+1}$ , and  $y_{i1}, \dots, y_{in}$  for  $1 \leq i \leq k$ . If the e-section is infinite, it will consist of  $x$ ,  $c$ ,  $b$ ,  $a_0$ ,  $a_1$ ,  $a_{i+1}$ , and  $y_{i1}, \dots, y_{in}$  for  $i \geq 1$ .

This completes the description of the construction of the graph. Now, we will check that  $G$  cannot be won with  $n - 1$  computable, but can be won with  $n$  computable cops or 1 non-computable cop. Moving forward, we will refer to the points  $a_1, \dots, a_i$  as the vertical segment of the e-section and the points  $c$ , and  $y_{jk}$  for  $j \in [1, i - 1]$  and  $k \in [1, n]$  as the horizontal section. Note that  $x$  is connected to every point in the horizontal section.

### **Why Can't n-1 Cops Following a Computable Strategy Win?**

If  $n - 1$  cops follow the strategy given by  $\Phi_e$ , they will be unable to win if the robber starts at  $a_1^e$  and moves up the vertical segment whenever possible.

### **Why Can n Cops Following a Computable Strategy Win?**

Suppose that  $n$  cops start at  $\lambda$ . We can assume the robbers start in an e-section because if the robber starts at  $\lambda$ , he loses.

All cops move to the  $x_e$  node. If the robber is in the horizontal section ( $c_e$ , or  $y_{ij}$ ), then one of the cops can move directly there and win.

Now, assume that the robber is on the vertical segment, meaning that he is at  $a_i$  for  $i \geq 1$ . Then, the cops can move to  $y_{(i-1)1}, \dots, y_{(i-1)n}$ . Then, one of the cops is at  $z_{i-1}$ . We know  $a_i$  is connected to  $a_{i-1}$ ,  $a_{i+1}$ ,  $z_{i-2}$ ,  $y_{(i-1)1}, \dots, y_{(i-1)n}$ ,  $y_{i1}, \dots, y_{in}$ . We

know that  $z_{i-1}$  is also connected to  $a_{i+1}$ ,  $a_{i-1}$ ,  $z_{i-2}$ ,  $y_{i1}, \dots, y_{in}$ , so if the robber moves to any spot that doesn't already have a cop, the cop at  $z_{i-1}$  can win.

### Why Can One Non-Computable Cop Win?

The cop can start at  $\lambda$ . Suppose the robber is in the e-section of the graph. The cop moves to  $x_e$ .

If the robber moves to one of the nodes in the horizontal section ( $c_e$ , or  $y_{ij}$ ), then the cop can move directly there and win on her next turn.

If the robber is at some  $a_i$ , the cop can move to  $z_{i-1}$ . If the robber moves to  $a_{i+1}$ ,  $a_{i-1}$ ,  $z_{i-2}$ ,  $y_{i1}, \dots, y_{in}$ , the cop can move directly there and win, as previously stated. The only other possible move is for the cop to go to  $y_{(i-1)n}$ . Then, the cop can move to  $z_{i-2}$ . The robber can either go to  $x$ ,  $z_{i-2}$ ,  $a_{i-1}$ , or  $a_i$ . In any of those cases, the cop can win on its next turn, so one non-computable cop can win.

□

### Computability With Infinitely Many Cops

We can see that if a graph is countably infinite, infinitely many cops can always win by just having a cop start at each vertex. The robber, then, is forced to share a vertex with one of the cops, so the cops win. Thus, we will require all infinitely many cops to start at a single vertex (which we will denote  $\lambda$ ).

Recall that in the finite version of the game with  $n$ -cops, a strategy was a function  $\Phi : \mathbf{N}^{n+2} \rightarrow \mathbf{N}$  that computed how to move the cops as a function of previous player moves and current player positions. However, we have to treat a strategy for infinitely many cops differently because we cannot code the location of infinitely many cops by a single number. A strategy in the infinite case is a function  $\Phi : \mathbf{N}^3 \rightarrow \mathbf{N}$ . We

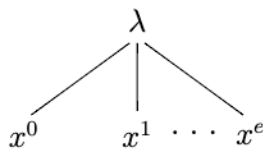
should let  $\sigma$  represent the positions of the robber in previous rounds. Let  $r$  represent the current position of the robber. Then, for each vertex  $v \in V(G)$ ,

$$\Phi : (\sigma, r, v) \mapsto \begin{cases} 1 & \text{if there is a cop at } v \\ 0 & \text{if there is no cop at } v \end{cases}$$

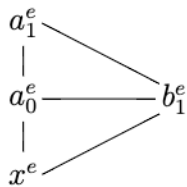
Once again,  $\Phi$  is a computable strategy if it respects the rules of the game. That is, if no neighbor of  $v$  contains a cop, then  $\Phi$  cannot put a cop at  $v$  in the next round.

**Theorem:** *There exists a computable graph  $G$  that can be won by one non-computable cop, such that no winning strategy exists with infinitely many computable cops starting at a designated node  $\lambda$ .*

*Proof.* To start,  $G$ , will consist of a root node  $\lambda$  and have infinitely many countable sections for the graph. We can assume that the cops start on the  $\lambda$  node. We will defeat the computable cops by using  $\Phi$  to check if the neighboring nodes of the node with the robber have a cop at them. We can note that  $G$  is the same as the graph Rachel Stahl constructed in her cop-win graph that cannot be won with a strategy up to relabeling. We will show that this graph also can deflect a strategy for infinitely many cops.

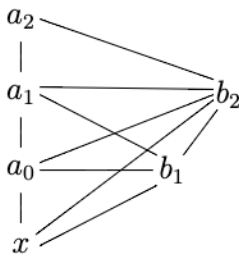


Each e-section of the graph should start consist of the following configuration. We can let the robber start at the node  $a_1^e$  for some e-section of the graph.



### Expanding the E-Section

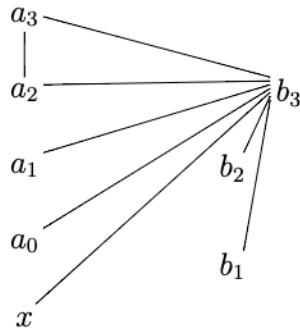
For ease of notation, we will drop the superscript on all points in the e-section of the graph throughout the construction of the graph. We use  $\Phi_e$  to check if a cop moves to a neighbor of the robber's starting location at  $a_1$ . Thus, we continue to check  $\Phi_e$  until a cop is moved to either  $a_0$  or  $c$ . If not, we take no action. If so, we add vertices  $b_2$  and  $a_2$  as with connections shown.



We connect  $a_2$  to  $a_1$  and connect  $b_2$  to all other points which are currently on the graph ( $x$ ,  $a_0$ ,  $a_1$ ,  $a_2$ , and  $b_1$ ).

After expanding  $G$ , the robber moves to  $a_2$  and we return to computing  $\Phi_e$  to check if a cop goes to a neighbor of the robber's new position. At least one of the cops just moved to either  $a_0$  or  $b_1$ . If the cops do not move within one space of the robber, the robber should stay at  $a_2$ .

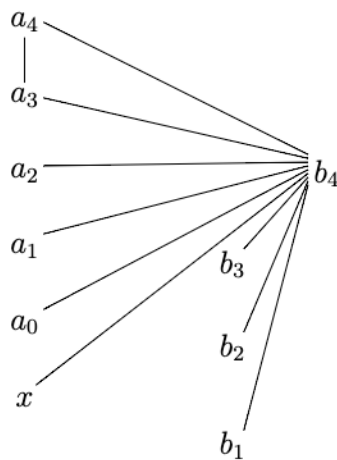
If a cop does move within one space of the robber, to either  $a_1$  or  $b_2$ , then we will expand the graph by adding vertices  $a_3$ , and  $b_3$  with connections as follows. For clarity, we will only show the new edges.



We connect  $a_3$  to  $a_2$  and connect  $b_3$  to all other points which are currently on the graph ( $x$ ,  $a_0$ ,  $a_1$ ,  $a_2$ ,  $a_3$ ,  $b_1$  and  $b_2$ ).

After expanding  $G$ , the robber moves to  $a_3$  and we return to computing  $\Phi_e$  to check if a cop goes to a neighbor of the robber's new position. At least one of the cops just moved to either  $a_1$  or  $b_2$ . If the cops do not move within one space of the robber, the robber should stay at  $a_2$ .

If a cop does move within one space of the robber, to either  $a_2$  or  $b_3$ , then we will expand the graph by adding vertices  $a_4$ , and  $b_4$  with connections as follows. For clarity, we will only show the new edges.





We connect  $a_4$  to  $a_3$  and connect  $b_4$  to all other points which are currently on the graph ( $x, a_0, a_1, a_2, a_3, a_4, b_1, b_2,$  and  $b_3$ ).

In general, for  $k \in \mathbf{N}$ ,  $a_k$  is connected to  $a_{k-1}, a_{k+1}, b_k, b_{k+1}, b_{k+2}, \dots$ . We also know that  $b_k$  is connected to  $x, a_0, \dots, a_k, b_j$  for  $j \in [1, k-1]$ .

In the end, the e-section will be either finite or infinite. If the e-section is infinite it will consist of  $x, a_0, a_i,$  and  $b_i$  for  $i \geq 1$ . If the e-section is finite, it will consist of  $x, a_0, a_i,$  and  $b_i$  for  $1 \leq i \leq k$ .

This completes the description of the construction of the graph. Now, we will check that  $G$  cannot be won with infinitely many computable cops all starting at  $\lambda$ , but can be won with one non-computable cop.

### **Why Can't Infinitely Many Computable Cops Win?**

We can see that if the robber moves up the vertical segment whenever possible, the cops will never be able to catch him as they are always at least two spaces away from the robber.

### **Why Can One Non-Computable Cop Win?**

The cop can start at  $\lambda$ . Suppose the robber is in the e-section of the graph and the cop moves to  $x_e$ .

If the robber moves to some  $b_i$ , then the cop can move directly there and win on her next turn.

Now suppose the robber is at  $a_i$ , then either  $b_{i+1}$  exists or there is no  $b_{i+1}$  node.

If there is a  $b_{i+1}$  node, we the cop can move to  $b_{i+1}$ . We know that  $a_i$  is connected to  $a_{i+1}, a_{i-1}, b_i, b_{i+1}, \dots$ . However,  $b_{i+1}$  is also connected to all of the vertices, so the cop can win on her next turn.

If there is no  $b_{i+1}$  node, the cop can move to  $b_i$ . Since,  $b_{i+1}$  was not added, the neighbors of  $a_i$  are  $a_{i-1}$  and  $b_j$  for  $j \in [1, i]$ . The node  $b_i$  is connected to each of these points, so the cop can win in her next turn.

□

## References

- (1) Bonato, Anthony and Nowakowski, Richard, *The Game Cops and Robbers on Graphs*, American Mathematical Society, (2011)./
- (2) Stahl, Rachel D., *Computability Theoretic Results for the Game of Cops and Robbers on Infinite Graphs*, *Archive for Math Logic* 61 (2022), 373-397.